



MODI: Use cases

28/03/2023

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MODI use cases

Demonstrere og evaluere på nivå 4 (L4)



Kilde: Einride

Overall - Challenges

- a. New business models for logistic operation
- b. Steps towards L4 motorway automated driving
- c. Standardization and harmonization
- d. Seamless integration of the PDI and the vehicles

MODI CCAM test corridor from Rotterdam to Oslo

- a. Identify critical parts PDI along the total corridor
- b. Solutions by cocreation between all stakeholders

UC Norway - Challenges

- a. Border crossing
- b. PDI infrastructure needed for level 4
- c. Seamless integration of automated subcomponents of the transport chain

UC Sweden - Challenges

- a. Access to confined area through gate
- b. Loading and unloading pallets and container
- c. Automated charging

UC Germany – Challenges

- a. Transition from Highway to confined area
- b. Reducing traffic load of HGV through the city
- c. Automated approach to charging area

UC The Netherlands - Challenges

- a. Coordinated Automated Driving on confined area
- b. Mixed traffic of manual operated and CCAM vehicles
- c. Logistic CCAM service for mix of confined area and public road destination















0

No Automation

Zero autonomy; the driver performs all driving tasks.

Driver Assistance

Vehicle is controlled by the driver, but some driving assist features may be included in the vehicle design. artial

Partial Automation

2

Vehicle has combined automated functions, like acceleration and steering, but the driver must remain engaged with the driving task and monitor the environment at all times.

3

Conditional Automation

Driver is a necessity, but is not required to monitor the environment. The driver must be ready to take control of the vehicle at all times with notice.

4

High Automation

The vehicle is capable of performing all driving functions under certain conditions. The driver may have the option to control the vehicle.

5

Full Automation

The vehicle is capable of performing all driving functions under all conditions. The driver may have the option to control the vehicle.





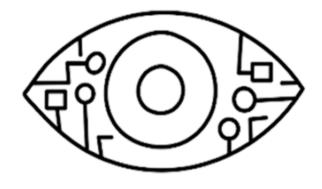
Kjerneteknologier for automatisert transport



Positioning



Communication



Human machine-readable infrastructure

Bilde: Tomas Levin



Portefølje

- Kjerneteknologier for automatisert transport

1 "Fremtidens behov for kommunikasjon i transportsektoren" Lambda

2019-2022



Statens vegvesen



Forskningsrådet







2 "Technology for advanced positioning in the transport system" **TEAPOT**

2020-2023







SINTEF





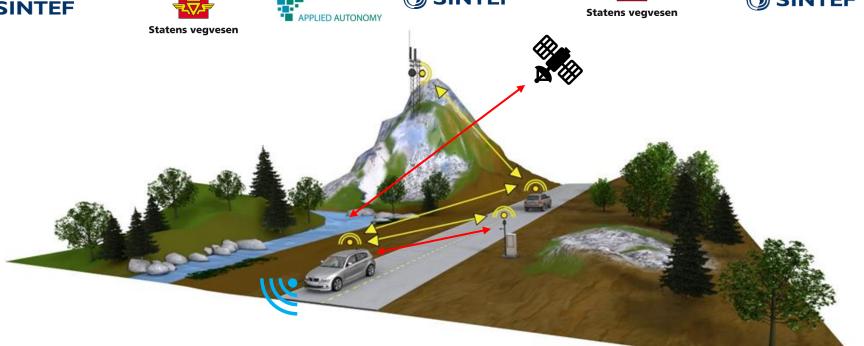
3 "Machine Sensible infrastructure under Nordic conditions" **MCSINC**

2022-2025











Portefølje

- Kjerneteknologier for automatisert transport

1 "Fremtid kommunik transports

2019-202







Høyt fokus på

pilotering og uttesting

og

samhandling på tvers av

relevante aktører

logy for advanced in the transport **APOT**







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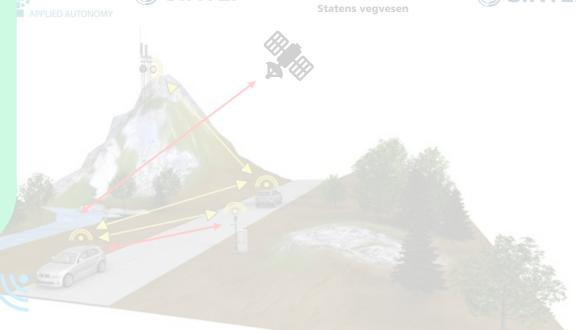
3 "Machine Sensible infrastructure under Nordic conditions" **MCSINC**

2022-2025













Portefølje

- Kjerneteknologier for automatisert transport

1 "Fremtid kommunik transports 2019-202









Høyt fokus på

pilotering og uttesting

og

samhandling på tvers av

relevante aktører

ogy for advanced in the transport **APOT**





Hovedaktiviteter SINTEF:

og
Leder WP2 "Use case definition
and impact assessment" inkludert
samhandlingsarenaer













Public roads: Prioritized L4 roads



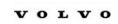












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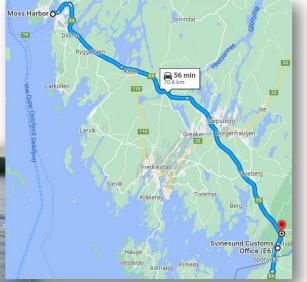


AISIKIO

Autonomous sea drones



In line with the call: focus on cocreation between stakeholders











Border crossing





Public roads: Prioritized L4 roads





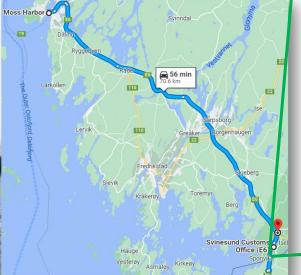
HAV

AISIKIO

Autonomous sea drones



In line with the call: focus on cocreation between stakeholders



Map data, reference frame, point cloud





Border crossing



Læringer på tvers av landegrenser: Oppkobling GNSS Tillatelse Fjern-grensesnitt (remote operator interface)





Public roads: Prioritized L4 roads







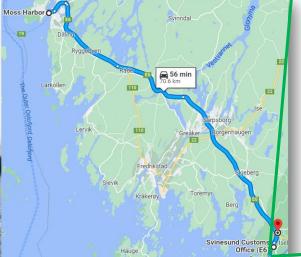


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Autonomous sea drones



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Læringer ved toll:

C-ITS løsninger

kontrollører

Lov og regulering uten sjåfør

Digital toll prosess - Digitall

Behov for interaksjon med

Border crossing





Public roads: Prioritized L4 roads

Moss Harbor







Sikkerhets-case for kjøring i høyere hastigheter Krav til PDI Teknologiske og regulatoriske gap



MOSS HAVN A S K O

Autonomous sea drones





Kartverket Map data, reference frame, point cloud





Border crossing



In line with the call: focus on cocreation between stakeholders





AISIKIO

Autonomous sea drones



In line with the call: focus on cocreation between stakeholders



Kartverket Map data, reference frame, point cloud





Border crossing



Læringer i tilknytningen til havn: Utforske verdien av heleelektrisk og helautomatisert transportkjede



Moss Ferjekai







Offentlig vei: Hvor klargjort er korridoren for kjøring på nivå 4?







Undersøke PDI og kjøretøy, samt deres samspill, for nivå 4 på strekningen Rotterdam-Oslo







Gjennomføre datainnsamling og analyse.













TRAFIKVERKET

Assessment of CCAM-implementation along MODI-corridor



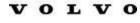






























Hovedperspektiver:

Kjøretøysprodusenter (VOLV, EIN, and DAF) Veimyndigheter (NMIW, VEJ, STA, BAST and NPRA) Logistikkoperatører (DFDS, ALI and GRU) Teknologileverandører (Q-Free) FoU (SINTEF, BAST)



Høna og egget

OEM + Teknologiperspektiv:

Myndighetsperspektiv:

Hva kan vi få, og hva er kravene?

Hva trenger dere, og hva kan dere få til?

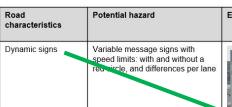
Høna og egget

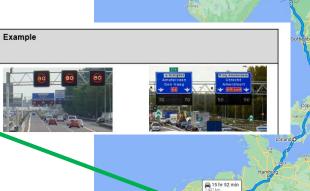
OEM + Teknologiperspektiv:

Please fill out the table below

Pain points – road elements – What is difficult?	Why is it difficult?	Suggestions for how to fix what is difficult - optional	Pain level – light, medium, hard
Tunnels (example!)	Loss of GNSS, light,	Augmented GNSS signals ITS-G5, sensor in vehicle for navigation (<u>e.g.</u> LiDAR),	Medium

Myndighetsperspektiv:





Felles forståelse og fremgangsmåte



Datainnsamling og analyse



THANKS FOR YOUR TIME!



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